

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

5 **Listing of Claims:**

1. (Original) A method for controlling the longitudinal movement of a vehicle (3), in particular by means of a longitudinal movement control system, wherein, for vehicle speeds above a threshold speed, the vehicle speed is adjusted to a higher selected set speed if no vehicle (8) traveling in front is detected, and if a vehicle (8) traveling in front is detected the distance from this vehicle (8) traveling in front is adjusted, characterized in that, below the threshold speed, the longitudinal movement of the vehicle (3) is controlled only if a vehicle (8) traveling in front is detected, the control below the threshold speed being carried out by adjusting the distance from the vehicle (8) traveling in front.

2. (Original) The method as claimed in claim 1, characterized in that a uniform operating control concept is used for controlling the longitudinal movement over the entire speed range.

3. (Currently Amended) The method as claimed in ~~one of the preceding claims~~ claim 1, characterized in that the control of the longitudinal movement below the threshold speed is carried out according to the concept of tracking functionality.

4. (Currently Amended) The method as claimed in ~~one of the preceding claims~~ claim 1, characterized in that the driver of the vehicle is provided with a signal, in particular an audible and/or visual signal, if the longitudinal movement control system is not active and/or cannot be activated below the threshold speed.

5 5. (Currently Amended) The method as claimed in ~~one of~~
~~the preceding claims~~ claim 1, characterized in that after the vehicle (3) is in
a stationary state, the driver is requested to enable automatic following of a
guide vehicle (8).

 6. (Currently Amended) The method as claimed in ~~one of~~
~~the preceding claims~~ claim 1, characterized in that the maximum
deceleration capacity is increased as the vehicle's own speed drops.

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 7. (Currently Amended) The method as claimed in ~~one of~~
~~the preceding claims~~ claim 1, characterized in that the surroundings of the
vehicle (3) are sensed in the area in front, in particular sensed without
gaps.

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 8. (Original) The method as claimed in claim 8,
characterized in that three lanes (4 - 6) are sensed.

 9. (Original) A longitudinal movement control system of a
20 vehicle (3), in particular for carrying out the method as claimed in one of the
preceding claims, having a control unit for controlling the longitudinal
movement of the vehicle (3) and having a detection device for vehicles (8)
traveling in front, characterized in that the system is active and/or can be
activated below a threshold speed only if a vehicle (8) traveling in front is
25 detected, the control when the system is active below the threshold speed
being carried out by adjusting the distance from the vehicle (8) traveling in
front.

 10. (Original) The system as claimed in claim 9, characterized
30 in that the detection device comprises sensors for sensing the short-range
area in front of the vehicle (3) without gaps.

11. (Original) The system as claimed in claim 10,
characterized in that a plurality of distributed beam sensors are provided.